

GLOBAL JOURNAL OF ENGINEERING SCIENCE AND RESEARCHES

FIXED POINT THEOREM IN FUZZY METRIC SPACE

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ABSTRACT

In this paper, we prove a fixed point theorem using compatible condition. Our result generalizes the result of Kang and Rhoades satisfying contractive condition of integral type.

Keywords- common fixed point, compatible mappings of type(P).

I. INTRODUCTION

Rhoades(1985) proved for pair of mappings which in turn was generalized by Kang and Rhoades (1996) using compatible condition defined by Jungck(1986). Branciari[1] obtained a fixed point result for a single mapping satisfying an analogue of Banach’s contraction principle for an integral-type inequality. The second author [6] proved two fixed point theorems involving more general contractive conditions.

II. PRELIMINARIES

Consider $\Phi = \{ \varphi : \mathbb{R}_+ \rightarrow \mathbb{R}_+ \}$ such that φ is nonnegative, Lebesgue integrable, and satisfies

$$\int_0^\varepsilon \varphi(t) dt > 0 \text{ for each } \varepsilon > 0 \tag{2.1}$$

Let $\Psi : \mathbb{R}_+ \rightarrow \mathbb{R}_+$ satisfy that

- (i) Ψ is nonnegative and nondecreasing on \mathbb{R}_+ ,
- (ii) $\Psi(t) < t$ for each $t > 0$,
- (iii) $\sum_{n=1}^\infty \Psi^n(t) < \infty$ for each fixed $t > 0$. where $\Psi = \{ \Psi : \Psi \text{ satisfies (i)-(iii)} \}$.

III. MATERIAL AND METHODS

Theorem (3.1): Let A, B, S and T be the mappings from a complete metric space (X, d) into itself satisfying the following conditions:

S and T are surjective

- (ii) One of A, B, S and T is continuous
- (iii) A, S and B, T are compatible pairs of type(P)

$$(iv) \int_0^{M(Ax, By, z)} \varphi(t) dt \geq \Psi \left(\int_0^{M(x, y, z)} \varphi(t) dt \right) \tag{3.1}$$

Where $k \in [0, 1)$, $\varphi \in \Phi$, $\Psi \in \Psi$, and

$$M(x, y, z) = \max \{ M(Sx, Ty, z), M(Sx, Ax, z), M(Ty, By, z),$$

$$\max \{ M(Sx, Ty, z), M(Sx, By, z), M(Sx, Ty, z), M(Ty, Ax, z), M(Sx, Ax, z), M(Sx, By, z), M(Ty, By, z), M(Ty, Ax, z) \}$$

$$\max \{ d(Sx, By, z), M(Ty, Ax, z) \}$$

$$(3.2)$$

when $M(x, y, z) = 1$ if $Sx = By$ and $Ty = Ax$. Then A, B, S and T have a unique common fixed point in X.

IV. RESULT AND DISCUSSION

Proof of theorem: If A, B, S and T be the mappings from a complete metric space (X, d) into itself then there exists a sequence $\{x_n\} \subset X$ with $x_0 \in X$,

$$Ax_{2n} = Tx_{2n+1} = x_{2n+1} \text{ and } Bx_{2n+1} = Sx_{2n+2} = x_{2n+2}$$

Now assume $x_{2n+1} \neq x_{2n+2}$ for each n . With $x = x_{2n}$, $y = x_{2n+1}$, then from (3.1) we have

$$\int_0^{M(Ax_{2n}, Bx_{2n+1}, z)} \varphi(t) dt \geq \psi \left(\int_0^{M(x_{2n}, x_{2n+1}, z)} \varphi(t) dt \right) \Rightarrow \int_0^{M(x_{2n+1}, x_{2n+2}, z)} \varphi(t) dt \geq \psi \left(\int_0^{M(x_{2n}, x_{2n+1}, z)} \varphi(t) dt \right) \quad (3.3)$$

Continuing this process, we have

$$\int_0^{M(Ax_{2n}, Bx_{2n+1}, z)} \varphi(t) dt \geq \psi \left(\int_0^{M(x_{2n}, x_{2n+1}, z)} \varphi(t) dt \right) \geq \dots \leq \psi_{2n}(d) \quad (3.4)$$

where $d = \int_0^{M(x_0, x_1, z)} \varphi(t) dt$. Then it is easily shown that $\{x_n\}$ is Cauchy, hence convergent. Call the limit p . Consequently the subsequences $\{Ax_{2n}\}$, $\{Bx_{2n+1}\}$, $\{Sx_{2n}\}$, $\{Tx_{2n+1}\}$ converge to p . Let $p = Sp = Ap$. Then $M(p, p, z) = \max \{M(Sp, Tp, z), M(Sp, Ap, z), M(Tp, Bp, z)\}$

$$\frac{\max \{M(Sp, Tp, z), M(Sp, Bp, z), M(Sp, Tp, z), M(Tp, Ap, z), M(Sp, Ap, z), M(Sp, Bp, z), M(Tp, Bp, z), M(Tp, Ap, z)\}}{\max \{M(Sp, Bp, z), M(Tp, Ap, z)\}} \quad (3.5)$$

Therefore $M(p, p, z) = \max \{M(p, Tp, z), 1, M(Tp, Bp, z)\}$

$$\frac{\max \{M(p, Tp, z), M(p, Bp, z), M(p, Tp, z), M(Tp, p, z), 1, M(p, Bp, z), M(Tp, Bp, z), M(Tp, p, z)\}}{\max \{M(p, Bp, z), M(Tp, p, z)\}} \quad (3.6)$$

Hence $M(p, Tp, z) \cdot M(p, Bp, z) = 1$ since $M(Tp, Bp, z) \geq M(Tp, p, z) \cdot M(p, Bp, z)$

So $p = Tp$, $p = Bp$ and (3.1) becomes

$$\int_0^{M(p, Tp, z)} \varphi(t) dt \geq \psi \left(\int_0^{M(p, Tp, z)} \varphi(t) dt \right) \quad (3.7)$$

which, from (3.3), implies that $p = Tp = Bp$.

Similarly, $p = Tp = Bp$ implies that $p = Sp = Ap$. We will now show that A, B, S and T satisfy (3.5).

$M(x, Sx, z) = \max \{M(Sx, TSx, z), M(Sx, Ax, z), M(TSx, BSx, z)\}$

$$\frac{\max \{M(Sx, TSx, z), M(Sx, BSx, z), M(Sx, TSx, z), M(TSx, Ax, z), M(Sx, Ax, z), M(Sx, BSx, z), M(TSx, BSx, z), M(TSx, Ax, z)\}}{\max \{M(Sx, BSx, z), M(TSx, Ax, z)\}} \quad (3.8).$$

Now we have $M(Sx, TSx, z) \geq M(Sx, Ax, z) \cdot M(Ax, TSx, z)$

$M(Sx, BSx, z) \geq M(Sx, Ax, z) \cdot M(Ax, BSx, z)$

$M(BSx, TSx, z) \geq M(BSx, Bx, z) \cdot M(Bx, TSx, z)$

on the considering above we have

$$\int_0^{M(Sx, TSx, z)} \varphi(t) dt \geq \psi \left(\int_0^{M(Sx, TSx, z)} \varphi(t) dt \right) \text{ a contradiction}$$

V. CONCLUSION

Hence S, A and T, B has a fixed point, that any fixed point of S, A is also a fixed point of T, B and conversely. Thus S, A and T, B have a common fixed point. Hence A, B, S and T has a common fixed point.

Suppose that T is continuous. Since B and T are compatible, then

$$TTx_{2n+1} = Tp \text{ and } BBx_{2n+1} = Tp.$$

So that $M(TTx_{2n+1}, BBx_{2n+1}, z) = 1 = M(SSx_{2n}, AAx_{2n}, z)$ as $n \rightarrow \infty$

VI. ACKNOWLEDGEMENT

The authors are thankful to the reviewers for their valuable suggestions to enhance the quality of our article.

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